

A RATE DISTORTION FRAMEWORK FOR 3D BROWSING

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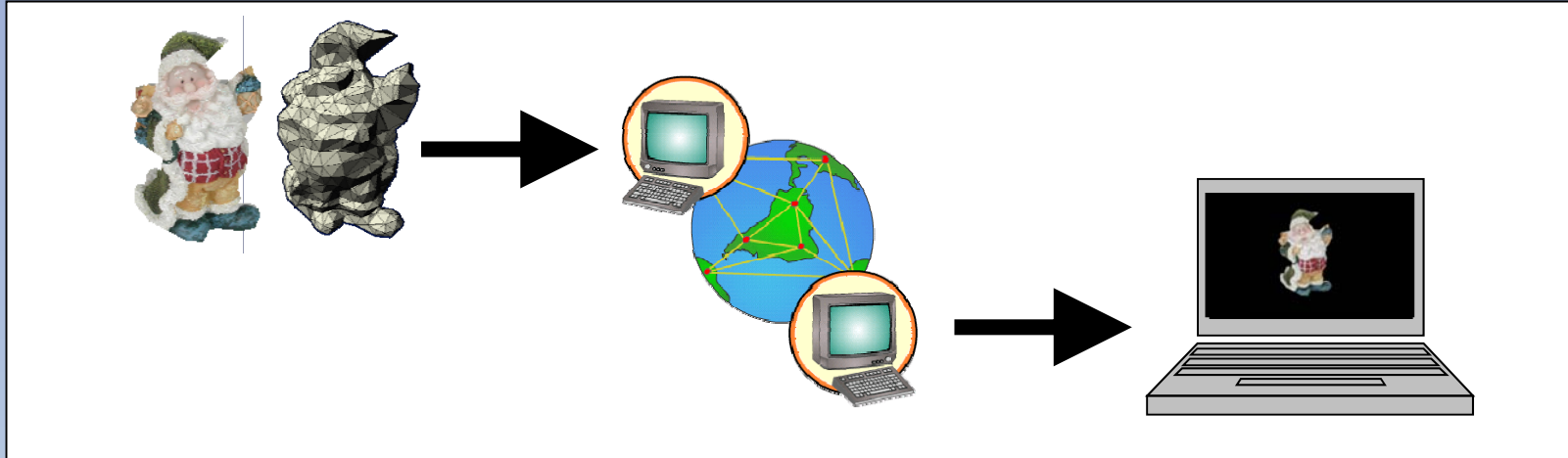
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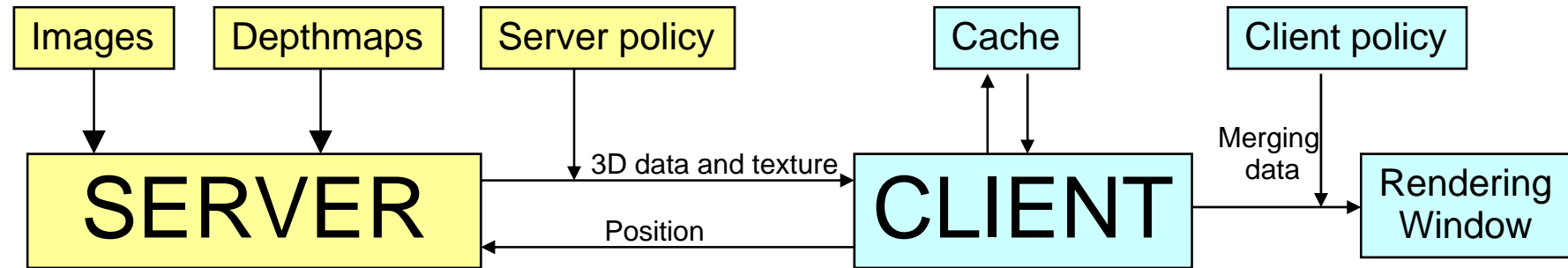


Objectives



- Interactive visualization system for 3D scenes
- Efficient remote browsing of complex 3D scenes
- Progressive transmission of the data available at server side
- Optimal bandwidth usage

System Overview



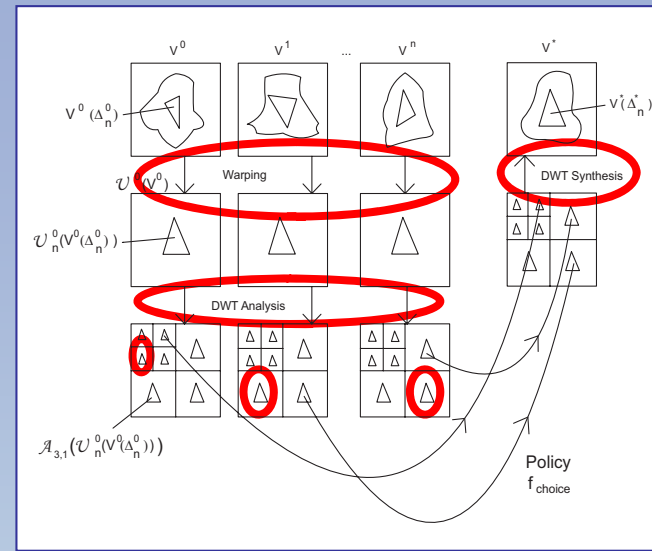
SERVER

- Stores images and depth information compressed in a scalable way (JPIP)
- A **server policy** to decide how to allocate transmission resources for geometry and texture

CLIENT

- Interactive 3D viewer
- Shows the best possible rendering with the information received from the server (**client policy**)
- Stores the received data

Client Overview



- The received views are reprojected on the target view using depth information
- The warped views are decomposed using the DWT
- A **minimum-distortion policy** is used to select samples from different views
- DWT synthesis is performed to reconstruct the required rendering

Distortion Framework

Scalable image compression



Perceptual factors



$$D_d^{i \rightarrow *}[p] = \sum_b W_{b \rightarrow d}[p] \cdot D_b^i \left[\left(W_{b \rightarrow d}^i \right)^{-1} (p) \right] + \overline{\sigma Z_d^*}^2 [p] \cdot \overline{g_d^{i \rightarrow *}} [p] \cdot \overline{|\omega_d|^2} \cdot \overline{E_d^{i \rightarrow *}} [p] + \tan \left(\max \{ 0, \cos^{-1} \langle \mathbf{e}^i, \mathbf{e}^* \rangle \} \right) \cdot \overline{E_d^{i \rightarrow *}} [p] + P$$



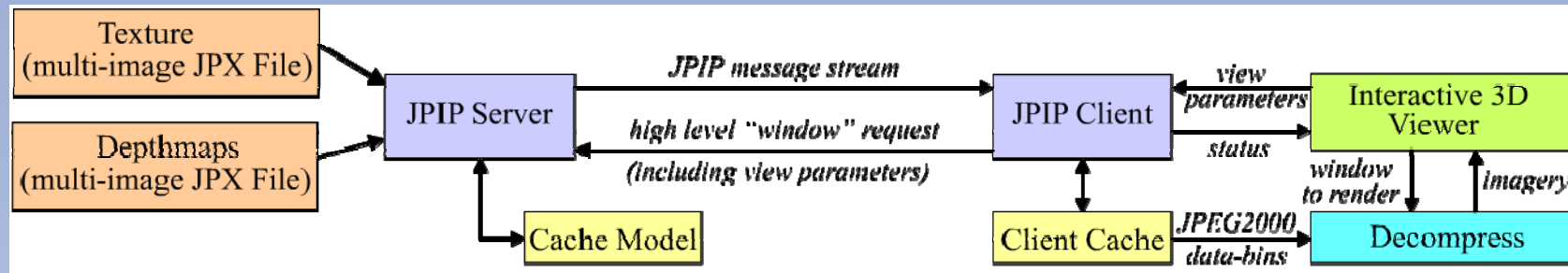
Geometry compression and acquisition uncertainty



Ligthing

- Estimation of how the various sources of distortion affects the rendered views [1]
- Samples' sources are chosen in order to minimize the distortion
- Used also for depth information

Server Overview



The server:

- Extends the functionalities of a standard JPIP server
- Holds JPEG2000 images divided in codeblocks
- Makes his own decisions on how to improve rendered views at client side

*How should the server distribute available transmission resources amongst the various elements of the original view images ?
(Assuming geometry already available at client side)*

Distortion Optimization

Distortion due to image compression

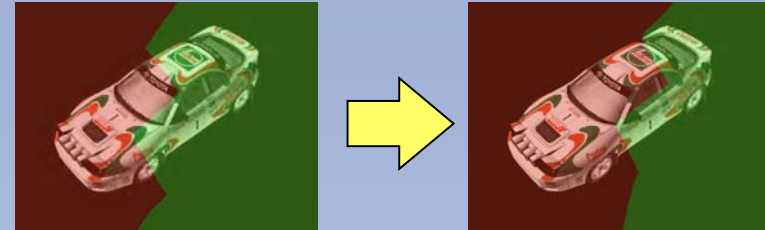
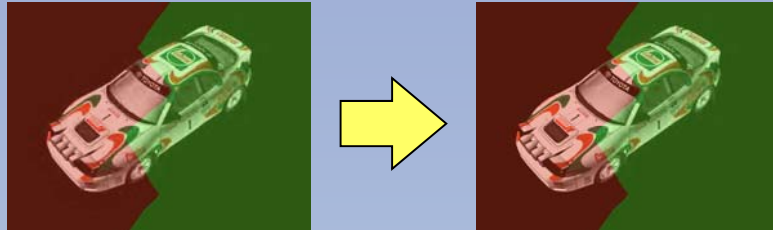
$$D^* \approx \sum_d \sum_{\mathbf{p}} \sum_i \underbrace{(\rho_d^i[\mathbf{p}])^2}_{\text{Blending choices}} \left(\underbrace{\Theta_d^{i \rightarrow *}}_{\text{Distortion due to geometry and lighting}}[\mathbf{p}] + \underbrace{\sum_b W_{b \rightarrow d}^i[\mathbf{p}] \cdot D_b^i \left[(\mathcal{W}_{b \rightarrow d}^i)^{-1}(\mathbf{p}) \right]}_{\text{Distortion due to image compression}} \right)$$

Blending choices

Distortion due to geometry and lighting

- Minimize the total distortion D^* in the rendered views
- Blending choices depend on the received data
- Lagrangian optimization subject to bandwidth constraint
- Can't recalculate blending weights after every iteration: two steps procedure

Two step optimization



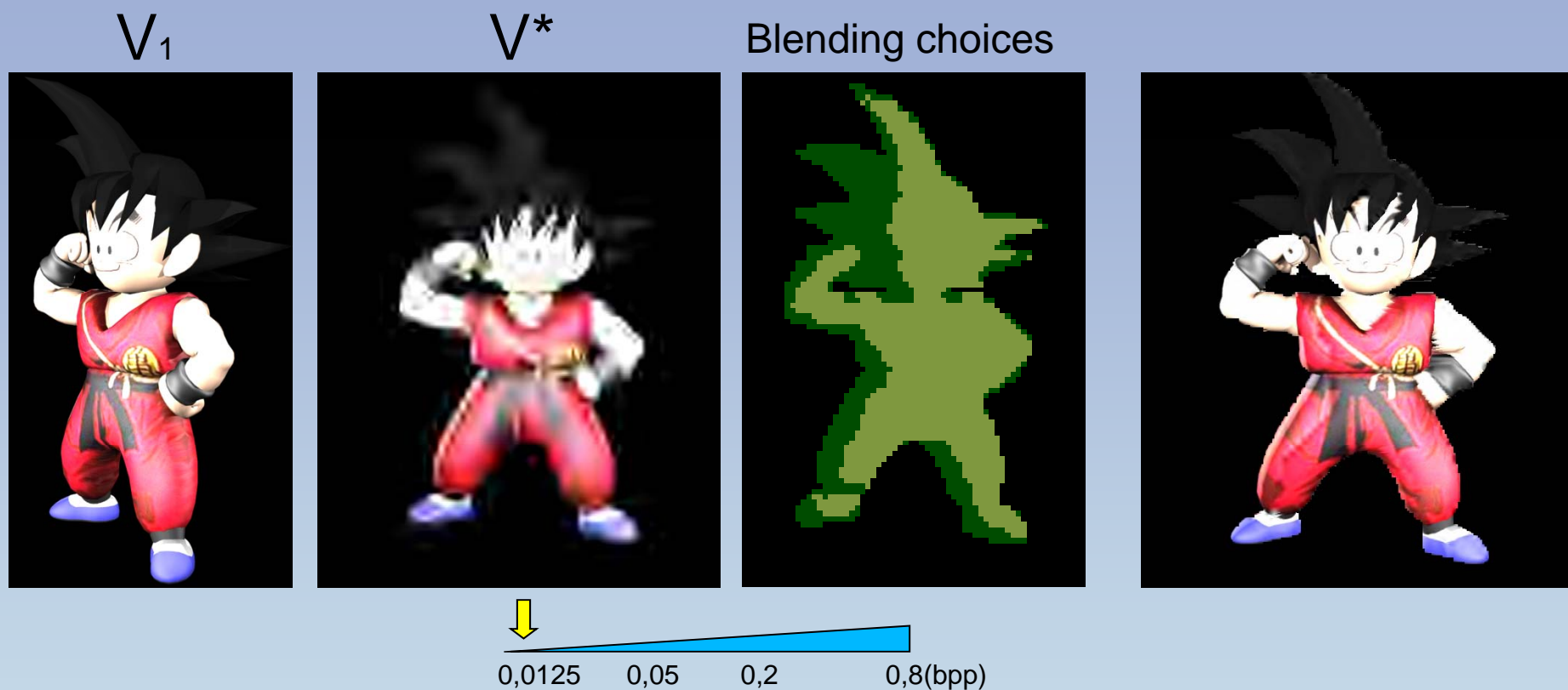
Reinforcing Enhancements

- Optimization solved with the assumption that the blending weights will not change
- θ_d constant, not considered in optimization
- Improvement of the code-blocks which contribute most strongly to the current view

Disruptive Enhancements

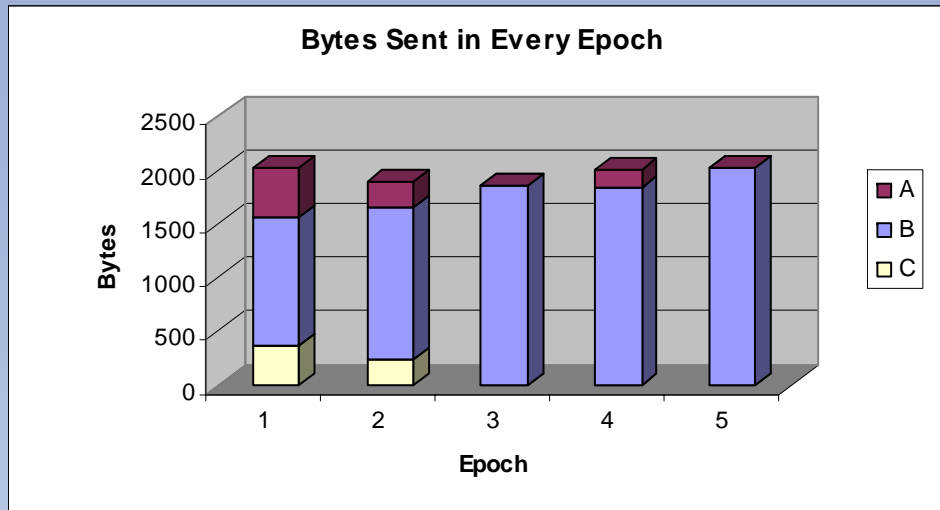
- Take into account changes in the blending choices due to new data transmitted to the client
- Force transmission of data from new images

Experimental Results: Client

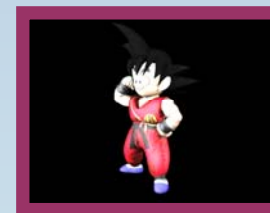
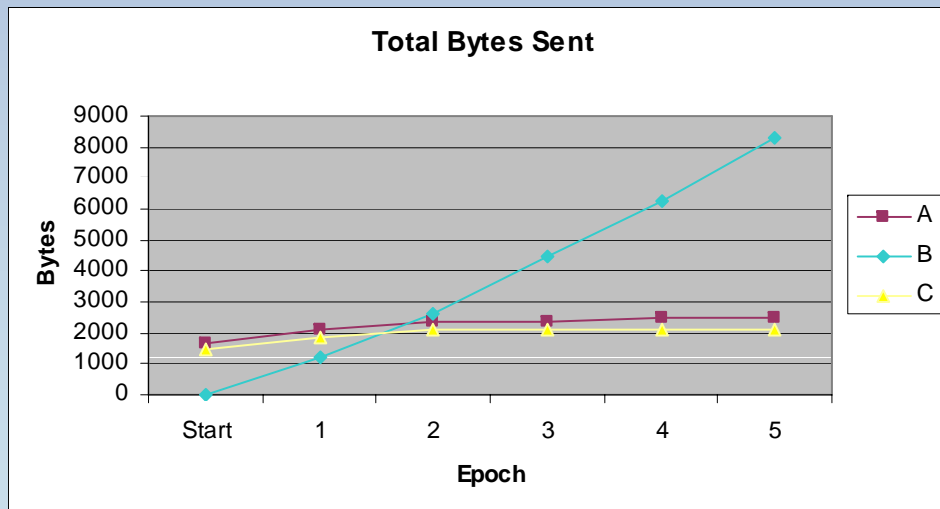


- At the beginning most samples warped from V_1 , good quality except for the region not visible in V_1
- As soon as more data become available for V^* , more and more samples are taken from it
- Finally almost all the samples are taken from V^*

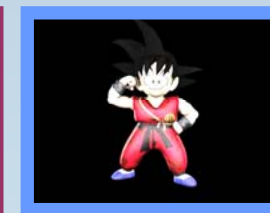
Experimental Results: Server



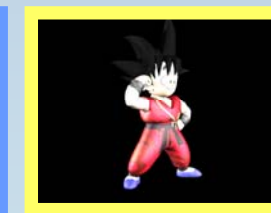
- Rendering from position B (no data available)
- ~2Kb available for A and C
- Improve A and C or start sending data for B ?
- In early epochs* improvement of A and C
- Data for B from disruptive enhancements
- Later most of the data transmitted for B



A


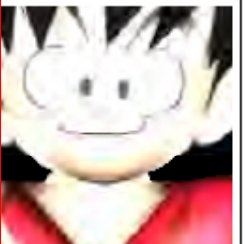


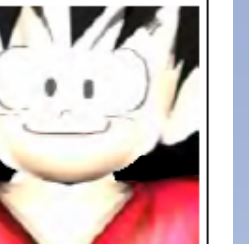





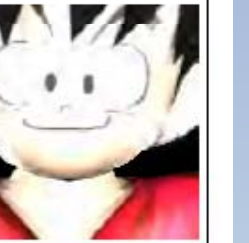


B



C

Experimental Results: Image quality

<i>1 View</i>	<i>No Data</i>					
<i>3 Views</i>						
Epochs	0	1	2	3	4	5

- Information from nearby views allows better image quality in early epochs
- At the end all samples taken from the closest view
- Exploit previously received data for interactive response
- Improve available views in fast movement

Conclusions

- Novel remote visualization scheme for 3D scenes
- Exploit progressive image compression and transmission techniques for 3D browsing
- Rate-distortion policy for view-synthesis and optimal allocation of the available bandwidth

Further Research

- Progressive geometry transmission
- Inclusion of perceptual factors within the distortion estimation
- Combined framework for optimal allocation of bandwidth between texture and geometry
- Extension to animated scenes (3Dvideo)